

# ISOMETRIC EMBEDDINGS<sup>1</sup>

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This note states results extending those of Nash [2] on isometric embeddings of Riemannian manifolds in euclidean spaces; proofs and further details will be given elsewhere.

Let  $M$  be a  $d$ -dimensional  $C^\infty$  manifold. For convenience, we assume throughout that manifolds, whether compact or not, are connected. A *metric* on  $M$  is defined to be a quadratic form on the tangent bundle of  $M$ ; note that there is no assumption of nondegeneracy. We shall assume that all metrics are  $C^\infty$ . A *Riemannian metric* on  $M$  is a metric whose restriction to the tangent space  $T_q$  at a point  $q \in M$  is positive definite, for all  $q \in M$ . A *pseudo-Riemannian*, or *indefinite*, *metric* is a metric whose restriction to the tangent space at each point is nondegenerate; if the nondegenerate restriction to  $T_q$  has  $n$  negative eigenvalues and  $p$  positive eigenvalues, with  $p+n=d$ , the metric is said to have signature  $(p, n)$  at  $q$ . The connectedness of  $M$  implies that the signature is independent of the choice of  $q \in M$ .

$R^m$  will denote euclidean  $m$ -dimensional space, with the standard flat, positive definite metric, unless otherwise indicated;  $R_n^p$  denotes euclidean  $(n+p)$ -dimensional space with flat metric of signature  $(p, n)$ . Thus  $R_0^m = R^m$ . Let  $F$  be a  $C^\infty$  map,  $F: M \rightarrow R_n^p$ , and let  $g$  be a metric on  $M$ ;  $F$  is said to be isometric for  $g$  if  $F^*(\cdot) = g$  where " $\cdot$ " denotes the metric for  $R_n^p$  indicated above. Note that if  $g$  is Riemannian and  $F$  is isometric for  $g$ , then  $F$  is necessarily an immersion and  $n+p \geq d = \dim M$ ; for a general metric  $g$ , however,  $F$  need not be an immersion. We shall concern ourselves with the question: given  $M$  and a metric  $g$  on  $M$ , for what  $R_n^p$  do there exist isometric immersions, or isometric embeddings,  $F: M \rightarrow R_n^p$ ?

**1. A geometric argument for general metrics.** Nash [2] guarantees the existence of isometric embeddings in some Riemannian euclidean space for any manifold with a Riemannian metric. The following argument reduces the general metric case to the Riemannian case, but requires higher dimension in the receiving euclidean space than necessary.

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**PROPOSITION.** *Suppose any Riemannian metric on  $M$  has an isometric immersion in  $R^k$ . Then any metric  $g$  on  $M$  has an isometric immersion (embedding) in  $R_{2d}^k(R_{2d+1}^k)$ .*

**OUTLINE OF PROOF.** Using Whitney's standard results on immersions and embeddings, one obtains a "large" immersion or embedding  $E: M \rightarrow R^{2d}$  or  $R^{2d+1}$  such that  $E^*(\cdot) + g$  is Riemannian. Then, if  $F$  is isometric for  $E^*(\cdot) + g$ ,  $F \times E: M \rightarrow R_{2d}^k$  (or  $R_{2d+1}^k$ ) is isometric for  $g$ , where  $F$  maps to the  $k$  positive-eigenvalue coordinates and  $E$  to the  $2d$  (or  $2d+1$ ) negative ones.

## 2. The compact case.

**THEOREM 1.** *Let  $M$  be compact,  $d$ -dimensional, with metric  $g$ . There is an embedding  $F: M \rightarrow R_{2d}^k$ ,  $k = d(d+5)/2$ , which is isometric for  $g$ .*

In [2], Nash shows that given a Riemannian metric  $g$  on a compact manifold  $M$ , there is an isometric embedding of  $M$  in euclidean  $d(3d+11)/2$ -dimensional space, where the euclidean space is flat Riemannian; the above theorem reduces the dimension required for the euclidean space and extends the result to arbitrary  $g$ , but the euclidean space is pseudo-Riemannian, even if  $g$  is Riemannian.

**3. The noncompact case.** The following Theorem 2 derives the existence of isometric immersions for noncompact manifolds from the isometric immersions of compact ones; the lemma, applicable to compact or noncompact manifolds, then provides isometric embeddings in the noncompact case. More specific results are given in Theorem 3.

**THEOREM 2.** *Suppose that, for any metric  $g$  on the  $2d+1$ -dimensional sphere  $S^{2d+1}$ , there is an isometric immersion of  $S^{2d+1}$  in  $R^n$ , where  $R^n$  has a flat Riemannian or pseudo-Riemannian metric. Then, if  $M$  is any  $d$ -dimensional manifold with metric, there is an isometric immersion of  $M$  in  $R^{2n}$ , where  $R^{2n}$  has a flat Riemannian or pseudo-Riemannian metric. Furthermore, if, for any Riemannian metric  $g$  on  $S^{2d+1}$ , there is an isometric immersion in  $R_n^p$ , then any manifold of dimension  $d$  with a Riemannian metric has an isometric immersion in  $R_{2n}^{2p}$ .*

**LEMMA.** *If a  $d$ -dimensional manifold  $M$ , compact or not, has an isometric immersion in  $R_n^p$  for any metric  $g$  on  $M$ , then  $M$  has an isometric embedding in  $R_n^{p+2d}$  for any  $g$ . Further, if, for every Riemannian metric  $g$ , there is an isometric immersion in  $R^p$ , then there is an isometric embedding in  $R^{p+2d+1}$ .*

**THEOREM 3.** *Every manifold  $M$  of dimension  $d$ , compact or not, has some isometric embedding in  $R^k$ ,  $k = (2d+1)(2d+6)$ , for every metric  $g$  on  $M$ . If  $g$  is a Riemannian metric,  $M$  has an isometric embedding in  $R^k$ ,  $k = (2d+1)(6d+14)$ .*

Theorem 3 improves Nash's result that a noncompact  $d$ -dimensional manifold  $M$  with Riemannian metric has an isometric embedding in  $R^k$ ,  $k = d(d+1)(3d+11)/2$ .

**4. The local case.** If a metric  $g$  is defined on an open set  $U$  in a manifold  $M$ , then, given an open set  $V$  with  $\bar{V} \subset U$ , there is a metric  $\bar{g}$  defined on  $M$  such that  $\bar{g}|_V = g|_V$ . Thus the global statements above imply corresponding local conclusions. However, in the local case, using A. Friedman's results [1] on the local analytic case, we can considerably improve the dimensional requirements for the cases of Riemannian and pseudo-Riemannian metrics.

**THEOREM 4.** *Let  $g$  be a metric defined on an open set in  $R^d$  and  $u$  a point of  $U$ . Suppose that  $g$  has signature  $(p_1, n_1)$  at  $u$ ,  $p_1 + n_1 = d$ . Then there is an open set  $V$ , with  $u \in V$ , such that there is an embedding of  $V$  in  $R^n$ ,  $n + p = d(d+3)/2$ , which is isometric for  $g|_V$ . If  $g$  is Riemannian at  $u$ , then  $n$  may be taken equal to 0. More generally,  $n$  and  $p$  may be chosen subject only to the restrictions  $n \geq n_1$ ,  $p \geq p_1$ ,  $n + p = d(d+3)/2$ .*

#### REFERENCES

1. A. Friedman, *Local isometric imbedding of Riemannian manifolds with indefinite metrics*, J. Math. Mech. 10 (1961), 625-649.
2. J. Nash, *The isometric imbedding problem for Riemannian manifolds*, Ann. of Math. (2) 63 (1956), 20-64.

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